In a nutshell: Step-by-step optimization

Given a continuous and differentiable real-valued function f of a real variable with an initial approximation of an extremum x_0 . This algorithm uses iteration and interpolating polynomials.

Parameters:

- $\varepsilon_{\text{step}}$ The maximum error in the value of the minimum cannot exceed this value.
- ε_{abs} The difference in the value of the function after successive steps cannot exceed this value.
- *h* An initial step size.
- *N* The maximum number of iterations.
- 1. Let $k \leftarrow 0$.
- 2. If k > N, we have iterated N times, so stop and return signalling a failure to converge.
- 3. Let and letting *j* take the values from 1 to *n* do the following:
 - a. If $f(x_k + h) < f(x_k), f(x_k h)$, continue calculating $f(x_k + nh)$ for positive integer values of nuntil $f(x_k + (n+1)h) > f(x_k + nh)$ and then set $x_{k+1} \leftarrow x_k + nh$,
 - b. otherwise, if $f(x_k h) < f(x_k)$, $f(x_k + h)$, continue calculating $f(x_k nh)$ for positive integer values of *n* until $f(x_k (n+1)h) > f(x_k nh)$ and then set $x_{k+1} \leftarrow x_k nh$,
 - c. otherwise, set $x_{k+1} \leftarrow x_k$.
- 4. If $|h| < \varepsilon_{\text{step}}$ and $|f(x_{k+1}) \min\{f(x_k h), f(x_k + h)\}| < \varepsilon_{\text{step}}$, we are done and return x_{k+1} .
- 5. Increment *k* and return to Step 2.

Acknowledgement: Jakob Koblinsky noted that I mistakenly copied $x_{k+1} \leftarrow x_k + nh$ in step 3b, which should be subtracting *nh*. This has been corrected.